

Efficient Capacity-Constrained Multicast in RC-Based P2P Networks

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Abstract

Application level multicast is independent of router infrastructure unlike router-based IP multicast. The existing DHT-based application level multicast protocols work efficiently as long as there is almost no churn; otherwise, their performances start degrading drastically, because DHT – based architecture cannot handle churn effectively. Besides, most of DHT-based multicast protocols consider single data source and do not consider per heterogeneity. In this work, we have considered an existing non-DHT based P2P architecture, viz., Residue Class based (RC-based) architecture which has already been shown to perform much better than some well-known DHT-based architectures from the viewpoints of speed of unicast communication and churn handling. We have presented a highly efficient capacity-constrained and any source multicast protocol suitable for the RC-based P2P architecture as mentioned above.

Keywords - P2P network; Residue class; Capacity constrained, multicast protocol

I. INTRODUCTION

Problems associated with the global deployment of multicast-capable routers, lack of support for network management, and also the scalability problem caused by the simultaneous presence of large number of multicast sessions, are some of the main reasons why the deployment of router-based IP multicast has been slow. Consequently, researches have started considering application level multicast as an alternative to IP multicast, because the former one can be deployed fast as it does not depend on router infrastructure [1], [2], [3]. Multicast protocols proposed in [4], [5], [6] focus on designing an

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optimized overlay multicast tree per multicast source. They can work well for certain applications, such as software distribution. There exist some interesting multicast protocols designed to work in DHT-based architectures [7], [8] However, none of these above mentioned works considers node heterogeneity. In addition, their performance degrades sharply as frequency of node (peer) movements in and out of the network increases.

In non-DHT-based structured P2P networks, overhead of maintaining the structural properties in the presence of churn has been shown to be much less compared to that in DHT-based structures [9], [10]. Note that frequent joining of new peers and leaving of existing peers is known as churn. However, very few such structures exist in the literature [9], [10]. Authors in [10] have proposed a unique way of designing non-DHT based P2P network architecture; they have designed a very effective multicast protocol suitable for the architecture, which is characterized by (1) any source multicast and (2) host heterogeneity, i.e. peers can have different capacities/degrees.

The work in [9] has used some idea from the work in [10] and modified it appropriately to make it suitable for their proposed non-DHT based architecture. A brief and clear description of how the protocol in [10] works and how our present contribution relates to that work has appeared in Section 3. However, some relevant preliminaries about the architecture [9] have appeared in Section 2, because we think that it will be helpful to have a better understanding of the materials stated in Section 3. The multicast protocol along with its performance have appeared in Section 4.

II. PRELIMINARIES

In this section, we start with a brief description of the Residue Class (RC)-based hierarchical structured P2P architecture [9]; note that we design our multicast protocols for this architecture. This architecture is a two-level structured one for interest-based peer-to-peer system [9], [11], [15].

A. Two Level Hierarchy

A resource is defined as a tuple $\langle R_i, V \rangle$, where R_i denotes the type of a resource and V is the value of the resource. A resource can have many values. For example, let R_i denote the resource type 'songs' and V' denote a particular singer. Thus $\langle R_i, V \rangle$ represents songs (some or all) sung by a particular singer V'. In the proposed model for interest-based P2P systems, it is assumed that no two peers with the same resource type R_i can have the same tuple; that is, two peers with the same resource type R_i can have the same tuple; that is, two peers with the same resource type R_i and $\langle R_i, V' \rangle$ such that $V' \neq V''$. However, this constraint can easily be relaxed [9]. In addition, let S be the set of all peers in a peer-to-peer system. Then $S = \{P^{R_i}\}, 0 \le i \le n - 1$. Here P^{R_i} denotes the subset consisting of all peers with the same resource type R_i and no two peers in P^{R_i} have the same value for R_i and the number of distinct resource types present in the system is *n*. Also for each subset P^{R_i} , P_i is the first peer among the peers in P^{R_i} to join the system.

The two level overlay architecture is shown in Fig. 1 and at each level structured networks of peers exist. At level-1, we have a ring network consisting of the peers P_i ($0 \le i \le n-1$). The number of peers on the ring is n which is also the number of distinct resource types. This ring network is used for efficient data lookup and so is named as transit ring network. At level-2, there are n numbers of completely connected networks (groups) of peers. Each such group, say G_i is formed by the peers of the subset P^{R_i} , ($0 \le i \le n-1$), such that all peers (ϵP^{R_i}) are directly connected (logically) to each other, resulting in the network diameter of 1. Each G_i is connected to the transit ring network via its group-

head P_i. Each peer on the transit ring network maintains a global resource table (GRT) that consists of n number of tuples. GRT contains one tuple per group and each tuple is of the form <Resource Type, Resource Code, Group Head Logical Address>, where Group Head Logical Address refers to the logical address assigned to a node by the proposed overlay P2P architecture. Also, Resource Code is the same as the group-head logical address. Any communication between a peer $p_i \\ \epsilon G_i$ and $p_j \\ \epsilon G_j$ takes place only via the respective group-heads P_i and P_j .

In this context, it may be noted that any structured P2P system, the mathematical model used to build the architecture defines neighborhood relations among peers. The mathematical model is intimately related to the efficiency of different data lookup schemes used in a given structured P2P system. We now state a brief sketch of the mathematical model used in this approach to realize the architecture [9].



Fig. 1 A two-level structured architecture with distinct resource types

B. Relevant Properties of Modular Arithmetic

Consider the set S_n of nonnegative integers less than n, given as $S_n = \{0, 1, 2, ..., (n-1)\}$. This is referred to as the set of residues, or *residue classes (mod n)*. That is, each integer in S_n represents a residue class (RC). These residue classes can be labelled as [0], [1], [2], ..., [n-1], where $[r] = \{a: a is an integer, a \equiv r (mod n)\}$.

For example, for n = 3, the classes are:

 $[0] = \{\dots, -6, -3, 0, 3, 6, \dots\}$ [1] = {...., -5, -2, 1, 4, 7, ... } [2] = {...., -4, -1, 2, 5, 8, ... }

Thus, any class r (mod n) of S_n can be written as follows: [r] = { ..., (r - 2n), (r - n), r, (r + n), (r + 2 n), ..., (r + (j-1).n), (r + j.n), (r + (j+1).n),} In the P2P architecture, the numbers belonging to different classes are used as the logical addresses of the peers; therefore, for the sake of simplicity only the positive integer values are used. Before we present the mechanism of logical address assignments, we state the following relevant property of residue class [9].

Lemma 1. Any two numbers of any class r of S_n are mutually congruent.

C. Assignments of Overlay Addresses

Assume that in an interest-based P2P system there are n distinct resource types. Note that n can be set to an extremely large value a priori to accommodate large number of distinct resource types. Consider the set of all peers in the system given as $S = \{P^{Ri}\}, 0 \le i \le n-1$. Also as mentioned earlier, for each subset P^{Ri} (i.e. group G_i) peer P_i is the first peer with resource type R_i to join the system. In the overlay architecture, the positive numbers belonging to different classes are used to define the following:

- (a) Logical addresses of peers in a subnet P^{Ri} (i.e. group G_i). Use of these addresses justifies the fact that all peers in G_i are directly connected to each other (logically) forming an overlay network of diameter 1. In graph theoretic term, each G_i is a complete graph.
- (b) Identifying peers that are neighbors to each other on the transit ring network.
- (c) Identifying each distinct resource type with unique code.

The assignment of logical addresses to the peers at the two levels and the resources happen as follows:

- 1) At level-1, each group-head P_r of group G_r is assigned with the minimum nonnegative number (*r*) of *residue class r (mod n)* of the residue system S_n .
- 2) At level-2, all peers having the same resource type R_r will form the group G_r (i.e. the subset P^{Rr}) with the group-head P_r connected to the transit ring network. Each new peer joining group G_r is given the group membership address (r + j.n), for j = 0, 1, 2, ...
- 3) Resource type R_r possessed by peers in G_r is assigned the code *r* which is also the logical address of the group-head P_r of group G_r .
- 4) Each time a new group-head joins, a corresponding tuple <Resource Type, Resource Code, Group Head Logical Address> is entered in the global resource table (GRT).

Below we have summarized the main characteristics of the architecture in the form of Lemmas and observations [9].

Remark 1. GRT remains sorted with respect to the logical addresses of the group-heads.

Definition 1. Two peers P_i and P_j on the ring network are logically linked together if $(i + 1) \mod n = j$.

Remark 2. The last group-head P_{n-1} and the first group-head P_0 are neighbors based on Definition 1. It justifies that the transit network is a ring.

Definition 2. Two peers of a group G_r are logically linked together if their assigned logical addresses are mutually congruent.

Lemma 2. Diameter of the transit ring network is n/2.

Lemma 3. Each group G_r forms a complete graph.

III. MOTIVATION AND OUR CONTRIBUTION

In [10], a non-DHT-based P2P architecture has been proposed in which a capacityconstrained multicast protocol has been designed. The architecture is an unrestricted ring of N nodes (peers) in a sense that a node can be anywhere on the ring unlike in DHT-based ring, such as Chord [12]. In the later, location of a node is unique, which makes the process of joining an existing structure by a new node very complex. According to the work in [10] each node n_i has its successor on the ring and also each node randomly selects c_i number of other nodes on the ring as its immediate logical neighbors; c_i is the degree/capacity of node n_i . We have highlighted below some significant contributions of the work.

First, any node can be a source and propagation of a multicast packet from a source node follows a tree structure created implicitly even though there is no explicit multicast tree creation unlike in the classical multicast protocols that use either the source-based tree approach [13] or the shared tree approach [14]. Therefore, it contributes to the communication speed of the multicast packets. Besides, the complicated process of maintaining an explicit tree can altogether be avoided.

The second one is that the value of the depth (number of levels) of the implicit tree can be controlled and it can be a system parameter. Depending on the value of the depth the protocol can combine tree traversal (in its phase 1) and sequential traversal along the ring (phase 2); effectively it transforms the multicast problem to a broadcast one within the scope of the overlay network.

The third one is that it has considered host heterogeneity; therefore, has taken into consideration the degree/capacity of a node while forwarding multicast packets to other nodes.

Authors in [10] have used the following definitions of hop complexity and communication complexity, which we shall use in our contribution. The hop complexity is the number of overlay hops needed by a multicast packet to arrive at any node and the communication complexity is the expected number of copies of a multicast packet that are transmitted in order to ensure that it arrives at all nodes. Note that the number of copies increases by one each time an intermediate node forwards the copy to its neighbor. Let *c* be the average node capacity. Then, the hop complexity has been shown to be $O(\log_c N)$ that is asymptotically optimal; the communication complexity is $[N + O(N/\log_c N)]$ that is close to *N*. On the other hand, if only sequential traversal is followed to send a multicast packet to any receiver, these are N/2 and *N* respectively.

We now illustrate briefly the working of the approach. Let a multicast source peer, say P_s with degree, say 2, has randomly selected two nodes P_i and P_j on the ring as its immediate neighbors. Let the respective degrees of P_i and P_j be 2 and 3.

First, P_s delivers the packet to P_i and P_j . Node P_i in turn delivers the packet to its two randomly selected neighbors, say P_k and P_l , which do the same to their respective randomly chosen neighbors. Node P_j does the same. When a node receives a duplicate packet, it sends a control packet asking the sender not to forward any more. Therefore, implicitly packet propagation follows a tree architecture. The work also suggests the following way to transmit the packet. In the above example, assume that P_i and P_j do not deliver the packet to their randomly selected immediate neighbors; instead, they forward the packet to their respective successors on the ring and a receiving node drops a packet if it is a duplicate packet, otherwise it forwards the packet to its successor. Therefore, it is actually a sequential traversal on the ring after the initial delivery of the packet by P_s to P_i and P_j . Note that peers P_s , P_i , and P_j effectively have formed a tree of depth one with P_s as its root and the other two as the leaves. Observe that any multicast group member never misses a packet and any packet arrives at every node. Therefore, it is clear that multicasting is being done via broadcasting.

Our Contribution

We have considered designing a highly efficient capacity-constrained overlay multicast protocol; it is designed specifically for an existing RC - based hierarchical and structured P2P architecture [9]. Such an architecture has been the choice for its structural advantages. The protocol is not restricted to a single data source and it incorporates peer heterogeneity as well. To determine the performance we shall use hop complexity and communication complexity as the parameters. As pointed out earlier that the architecture in [10] is a ring that consists of N peers in the overlay network. Our architecture is a 2-level one. Number of nodes (group-heads) n on the level-1 ring is just the number of distinct resource types and in any group (cluster) at level 2 there can be any number of nodes. Note that the number of distinct resources n is much smaller than the total number of nodes N on the ring in [10]. Therefore, for ring traversal at level 1 in our architecture, communication complexity is just *n* instead of N and the hop complexity is just n/2 instead of N/2. It has inspired us to use some idea from [10], especially transforming the multicast problem to a broadcast one and appropriately augmenting it with ours to design a highly efficient any source capacity-constrained multicast protocol suitable for the RCbased architecture with much less hop and communication complexities compared to the work in [10]. In this paper, we shall consider inter-group multicast communication as it is much more complex than the intra-group one.

IV. OVERLAY MULTICAST PROTOCOL

We shall use the following notations in the proposed protocol. Assume that the kth peer in group G_i (with group-head P_i) wants to multicast packets. This source peer is denoted as $p^{s}_{i,k}$ and the group-head P_i will then be denoted as P^{s}_{i} and be called as the source group-head, even though it is not the actual source of multicast . The degree/capacity of P^{s}_{i} is denoted as c^{s}_{i} . In a similar way, the mth receiver peer (a multicast group member) in group G_j is denoted as $p^{r}_{j,m}$ and the corresponding group-head as P^{r}_{j} . This group-head will be called a receiver group-head, because even though it may or may not be a multicast group member, it must deliver multicast packets received from other group-heads to peers like $p^{r}_{j,m}$. We assume that the receiver peer $p^{r}_{j,m}$ sends a join request to its group-head in order to receive multicast packets sent for this multicast group.

Note that any group-head can itself be a multicast group member or a multicast source as well; besides, a receiver may exist in the same group in which a source peer exists. Finally, in our architecture, each group-head has a global resource table (*GRT*) that has every group-head's logical as well as IP addresses. This piece of information is essential to our proposed protocol. In this protocol, n_r denotes the number of receiver group-heads and *mcast_msg* denotes a multicast message. We will consider the following two possible cases: (1) $c_i^s \ge n_r$ and (2) $c_i^s < n_r$. The protocol appears in Figs. 2a and 2b.

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Protocol OM-cast

Case	1: $c^s_i \ge n_r$
1.	source Peer p ^s _{i,k} unicasts <i>mcast_msg</i> to group-head P ^s _i
2.	P ^s _i unicasts <i>mcast_msg</i> to each of the nr receiver group-heads
	// P^{s}_{i} gets the IP addresses from its GRT; one logical hop to each group-head
3.	 if a receiver group-head P^r_j is also a multicast group member, then it keeps a copy of <i>mcast-msg</i> to itself P^r_i unicasts <i>mcast_msg</i> to each receiver p^r_i in its group.
	else
	P_{j}^{r} unicasts <i>mcast_msg</i> to each receiver $p_{j,m}^{r}$ in its group
	// one logical hop from group-head to each receiver since a group is a complete graph total number of copies of mcast_msg is $(n_r + number of receivers in groups)$

Fig. 2a Multicast protocol: Capacity of the group head $(c^{s_i}) \ge$ number of receiver group-heads (n_r)

Case 2: $c^{s_i} < n_r$ 1. P_{i}^{s} unicasts *mcast msg* to each of the c_{i}^{s} group-heads // P^{s_i} gets the IP addresses of the c^{s_i} receiver group-heads from its GRT; one logical hop to each group-head. 2. P^s_i forwards *mcast msg* to its successor on the level-1 ring 3. Each receiver group-head P_i^r unicasts *mcast msg* to each receiver $p_{i,m}^r$ in its group // one logical hop from group-head to each receiver since a group is a complete graph 4. if P_{i}^{r} is a multicast group member, then keeps a copy of mcast-msg to itself forwards mcast_msg to its successor on the level-1 ring else forwards mcast msg to its successor on the level-1 ring 5. if a successor group-head receives a duplicate message, then it discards the message and stops forwarding else if a successor group-head is both a receiver group-head and a multicast group member, then keeps a copy of *mcast-msg* to itself; it unicasts *mcast_msg* to receivers in its group; forwards the mcast-msg to its successor on the ring; else if a successor group-head is a receiver group-head, then it unicasts mcast msg to receivers in its group forwards the mcast-msg to its successor on the ring else

it forwards the *mcast-msg* to its successor on the ring

Fig. 2b Multicast protocol: Capacity of the group head $(c^{s_i}) <$ number of receiver group-heads (n_r)

Performance

We observe that when $c^{s_i} \ge n_r$, a packet takes a maximum of 3 overlay hops to reach a multicast group member from a source. However, in the case of $c^{s_i} < n_r$, the hop complexity is O(n). It is interesting to note that the capacity of the source group-head has apparently no significant effect on the hop complexity, which is not the case in [10] which offers a hop complexity of $O(\log_c N)$. We note that in general $n \ll N$, therefore, our proposed architecture offers improved performance than the one in [10].

In [10] the communication complexity is $[N + O(N/\log_c N)]$ that is close to N. In our proposed work, maximum number of copies from a source to a multicast group-member is 3 when $c^{s_i} \ge n_r$. When $c^{s_i} < n_r$, it is $(n + (c^{s_i} + 1) + 1)$ and it is close to n since in general, $c^{s_i} \ll n$. Therefore, we conclude that our architecture offers improved performance than in [10] in the case of communication complexity as well.

V. CONCLUSION

In this paper, we have considered an existing RC - based P2P architecture for its structural advantages over DHT-based architectures. We have used some of its unique structural characteristics to design an efficient overlay multicast communication protocol. The multicast protocol is not restricted to a single data source and it incorporates peer heterogeneity. We have used the idea of transforming the multicast problem to a broadcast one [10] and appropriately augmented it to design the proposed protocol with less hop and communication complexities compared to the work in [10]. Future work is directed at building architecture for P2P federation using the idea of this work.

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